

# EasyPalletStation

## Modular dual-pallet architecture for cobots, industrial robots and mobile automation

A robust, floor-anchored palletizing platform that combines one or two pallet stations with the pedestal, robot and safety concept best suited to the application.



● Compatible with 99% of modern cobots

● Many industrial robots

● Configurable for mobile robots / AMRs



### ORDER THE ROBOT ADAPTER PLATE

Select the robot model in the EasyRobotics configurator and order the matching adapter plate separately. If no standard interface fits, a custom plate can be engineered.

# Built for stable, repeatable palletizing

High-mass steel modules create a defined reference for pallet placement, robot reach and repeatable end-of-line handling.



STRUCTURAL PLATFORM

**160 kg**

EPS-1000 dual-station set without pedestal

**220 kg**

EPS-1000 with standard pedestal

**950 mm**

Standard fixed pedestal height

**Floor anchored**

Required for production use

## ROBUSTNESS ARCHITECTURE

1

### Rigid steel structure

The robust frame resists movement and provides a repeatable mechanical datum.

2

### Open pallet access

The low station height allows straightforward pallet exchange by pallet truck or forklift.

3

### Flexible pallet geometry

Adjustable positioning supports common pallet standards from EUR to GMA and APAC.

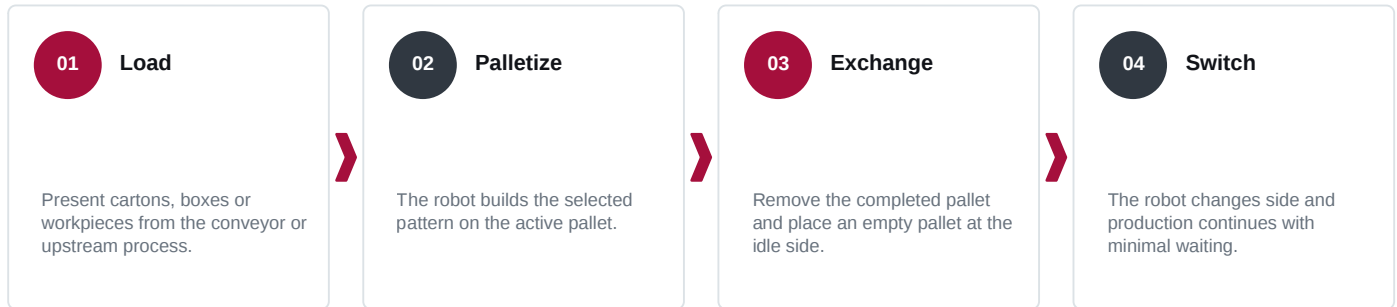
4

### Modular pedestal interface

Use the standard fixed pedestal or engineer a different pedestal, lifting column or mobile robot interface.

# Dual-pallet flow keeps the process moving

With two pallet positions, the robot can continue on one side while the completed pallet is exchanged on the other.



## Supported pallet formats

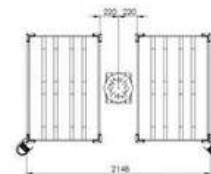
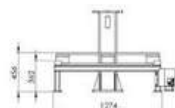
|       |                |
|-------|----------------|
| GMA   | 1219 x 1016 mm |
| EUR 1 | 1200 x 800 mm  |
| EUR 3 | 1200 x 1000 mm |
| GLOB  | 1067 x 1067 mm |
| APAC  | 1100 x 1100 mm |
| AUS   | 1165 x 1165 mm |

## PALLET FORMAT FLEXIBILITY



## Operational benefits

- One or two pallet positions
- Good operator and forklift access
- Fast changeover between left and right
- No compressed-air requirement
- Pallet detection is project-specific



Pallet-present sensors are not included as standard. Add detection and interlocks when required by the risk assessment or process sequence.

# One platform. Multiple robot architectures.

The mechanical station can be configured around the robot, reach envelope, payload, plant logistics and required safety concept.



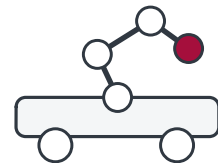
## Collaborative robots

Designed for 99% of modern cobots. Validate reach, base load, tool and pallet geometry.



## Industrial robots

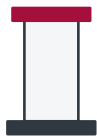
Many compact and medium industrial robots can be integrated after engineering review of mass, moments, dynamics and guarding.



## Mobile robots and AMRs

The station can be adapted to different mobile robots, AMRs, AGVs or mobile manipulators with project-specific docking, height and handover interfaces.

## PEDESTAL ARCHITECTURE



### Standard fixed pedestal

950 mm



### Alternative fixed height

Project-specific



### Lifting column

For variable stack height



### Mobile robot interface

Custom dock / handover



### Do not omit the adapter plate.

Select the exact robot model in the online configurator. The plate is ordered separately; a custom interface can be engineered when required.



ROBOT SELECTION CHECK

Reach | payload | base moments | mounting pattern | pallet envelope | safety concept

# Configure the station around the process

Start with a single pallet module or specify the complete dual-pallet set with a central pedestal.

## EPS-1000 | Dual-pallet set

1 x fixed pedestal, 2 x pallet stations



|                   |                                   |
|-------------------|-----------------------------------|
| Station module    | 1274 x 874 x 362 mm               |
| Configured weight | 220 kg                            |
| Pedestal height   | 950 mm                            |
| Pallet positions  | 2                                 |
| Best for          | Continuous left/right palletizing |

## EPS-1001 | Single pallet station

1 x pallet station, without pedestal



|                  |                                     |
|------------------|-------------------------------------|
| Station module   | 1274 x 993 x 362 mm                 |
| Module weight    | Confirm in quotation                |
| Pedestal         | Not included                        |
| Pallet positions | 1                                   |
| Best for         | Custom layouts and staged expansion |

### TYPICAL BUILD-UPS

1

Single station + existing robot

2

Dual station + fixed pedestal

3

Dual station + lifting column

4

Station + mobile robot logistics

Overall installed envelope depends on pallet format, pedestal, robot, guarding and safety devices.

# Options and engineered integration

Combine published options with project-specific engineering to match the robot, factory layout and safety strategy.

## PUBLISHED OPTION

### SC-1000 | Safety Scanner Cover



Mechanical cover for the selected scanner arrangement. Scanner hardware and safety programming are application-specific.

### Robot adapter plate | Configurator item



Select the robot-specific plate separately. A custom plate is available when the standard interface does not fit.

## ENGINEERED OPTIONS

### 1 Alternative pedestal

Fixed height, lifting column or customer pedestal.

### 2 Mobile robot adaptation

AMR / AGV docking, mechanical handover and height matching.

### 3 Pallet detection

Sensors, confirmation logic and interlocks.

### 4 Conveyor integration

Infeed height, pick position and control handshake.

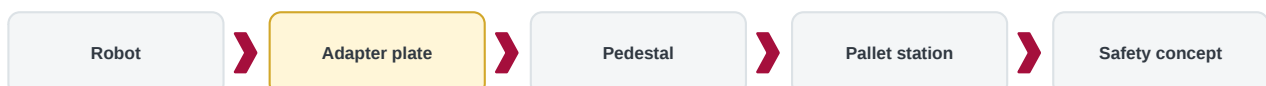
### 5 Custom pallet geometry

Stops, guides and frames for the selected pallet or load carrier.

### 6 Industrial robot package

Robot console, adapter, anchoring and safety concept.

## CONFIGURATION PRINCIPLE



Options may require project engineering, safety validation and a separate quotation.

# Install for stability. Validate the complete cell.

The platform is one component of the automation system. Final safety and conformity depend on the complete application.

1

## Verify layout and floor

Check pallet access, robot reach, concrete quality and safety distances.

2

## Anchor the stations and pedestal

Use floor anchors suited to the substrate and expected loads.

3

## Install adapter plate and robot

Follow the robot manufacturer's mounting requirements.

4

## Set pallet positions

Configure stops and clearances for the selected pallet standards.

5

## Integrate process and safety

Connect conveyor, gripper, scanner or guard system and cell control.

6

## Validate before production

Complete risk assessment, stop-time tests, reach review and functional validation.

## Technical summary

|                        |                                                               |
|------------------------|---------------------------------------------------------------|
| Pallet positions       | EPS-1000: 2   EPS-1001: 1                                     |
| Floor anchoring        | Required                                                      |
| Teach pendant mounting | Flexible - base or floor                                      |
| Pallet sensors         | Not included as standard                                      |
| Controller enclosure   | Not included                                                  |
| Compressed air         | Not required                                                  |
| Standard interface     | None                                                          |
| Robot compatibility    | 99% of modern cobots; many industrial robots after validation |



The station does not constitute a complete CE-marked robot cell. The integrator is responsible for the final risk assessment, guarding, safety performance and conformity of the complete machinery.

# Ordering overview

Published product references and the separately required robot interface.

| Order no.               | Product / configuration                                                      | Scope                                                                        |
|-------------------------|------------------------------------------------------------------------------|------------------------------------------------------------------------------|
| EPS-1000                | EasyPalletStation dual-pallet set                                            | L: 1274 mm W: 874 mm H: 362 mm   1 fixed 950 mm pedestal + 2 pallet stations |
| EPS-1001                | EasyPalletStation single module                                              | L: 1274 mm W: 993 mm H: 362 mm   1 pallet station, no pedestal               |
| SC-1000                 | Safety Scanner Cover                                                         | Optional mechanical cover                                                    |
| Configurator item       | Robot-specific adapter plate                                                 | Must be selected and ordered separately                                      |
| Quotation / engineering | Alternative pedestal, mobile robot interface, sensors and custom integration | Project-specific scope                                                       |



REMEMBER THE ADAPTER PLATE

Select the exact robot model in the EasyRobotics configurator. The adapter plate is not assumed to be included unless stated in the quotation. A custom interface can be engineered when required.



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CONFIGURATOR / PARTNER PORTAL

[easyrobotics.biz/login](https://easyrobotics.biz/login)

Select robot model, adapter plate and project options.



Errors and omissions excepted. Technical data, dimensions, weights, illustrations, product names, order references and availability are subject to change without notice. The current quotation, approved project drawings and order confirmation take precedence. Robot compatibility and the safety of the complete cell must be validated for the actual application.